

# OV/4-5 Progress in Disruption Prevention for ITER

**E.J. Strait, with**

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<sup>12</sup> Lehigh University    <sup>13</sup> Istituto di Fisica del Plasma (Milano)    <sup>14</sup> Institute of Plasma Physics (Hefei)

# Burning Plasmas Must Operate with Very Few Disruptions

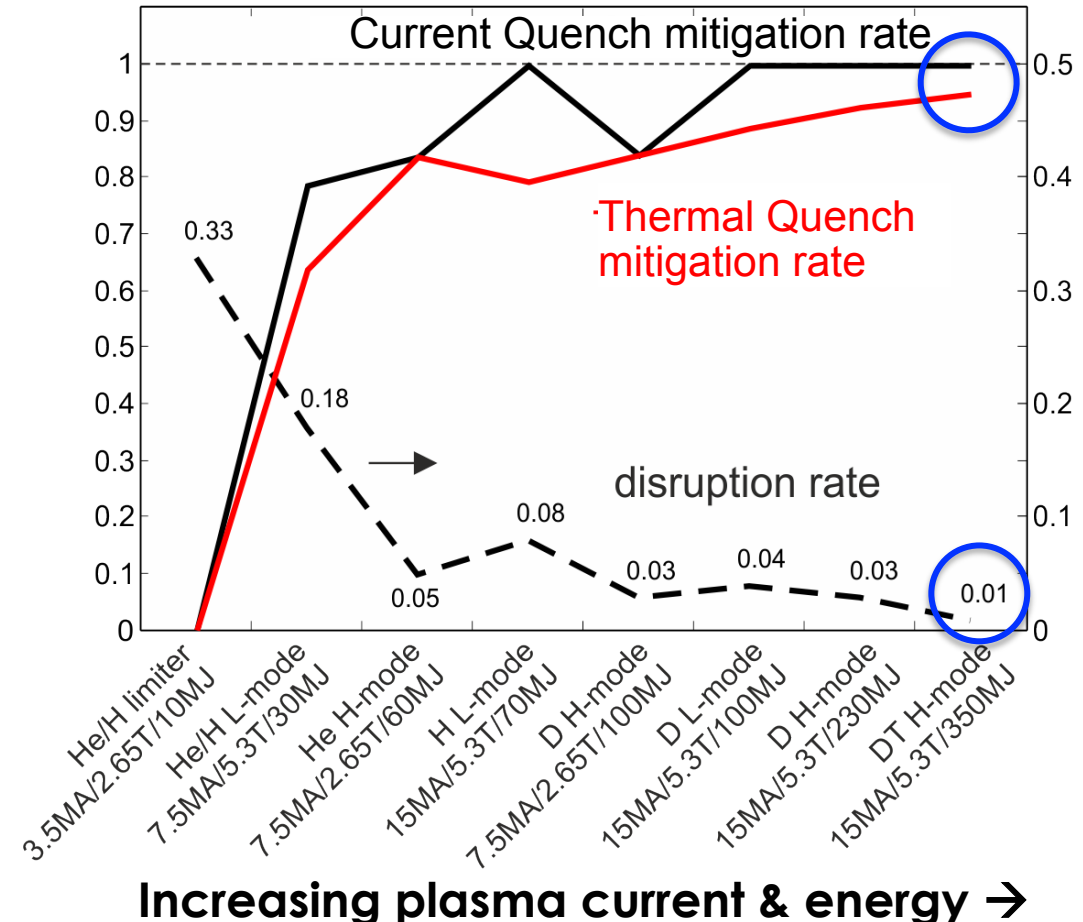
At full Q=10 performance, ITER's disruption budget requires:

- **Nearly disruption-free operation**
  - $\leq 1$  disruption per 100 pulses
- **Accurate prediction of disruptions**
  - Mitigation rate  $\sim 95-100\%$

**Mitigation of disruptions is necessary, but not sufficient.**

**ITER also requires highly reliable methods for preventing disruptions.**

A potential scenario for ITER's disruption and mitigation rates



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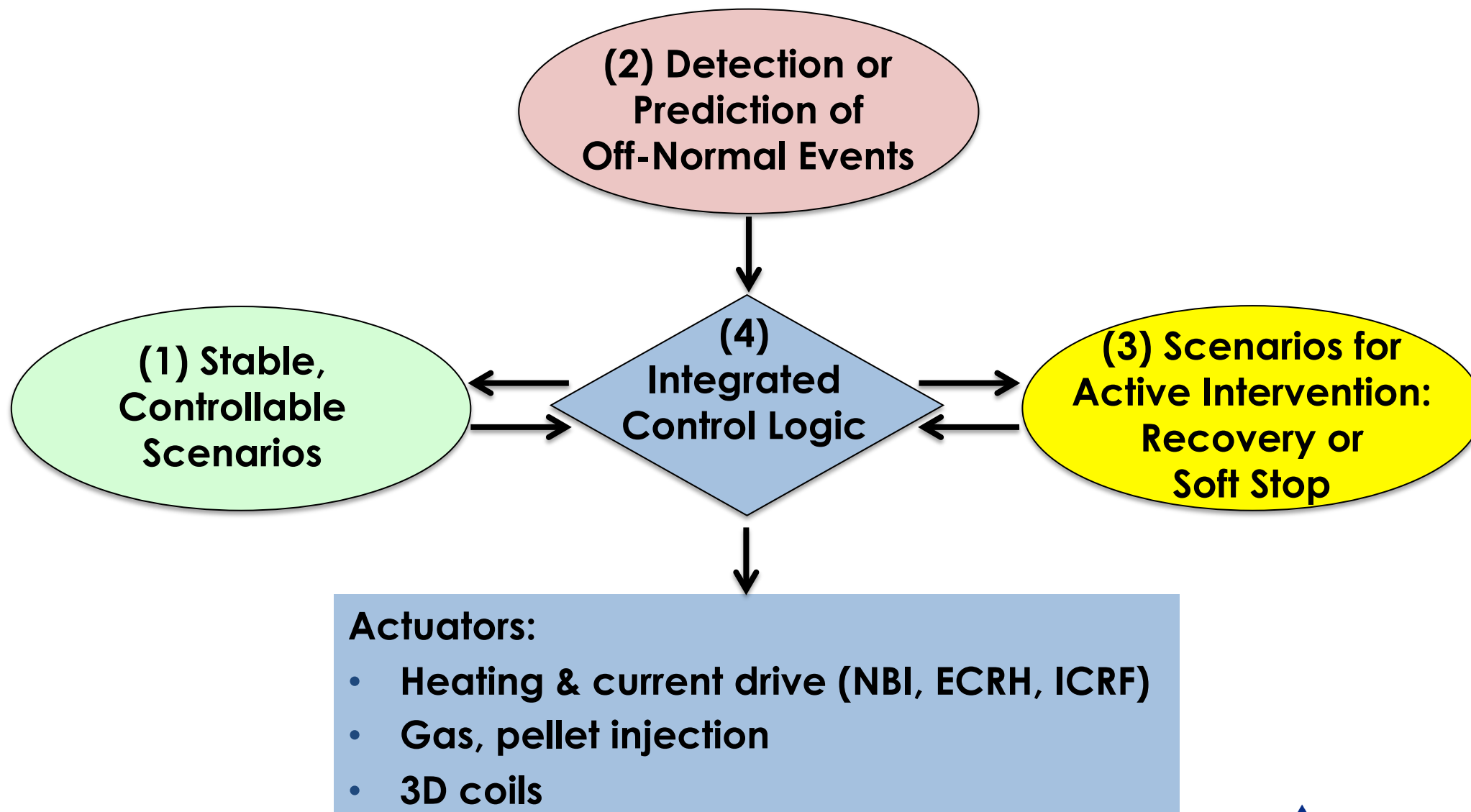
**ITER also requires highly reliable methods for preventing disruptions.**

## Scope of this talk:

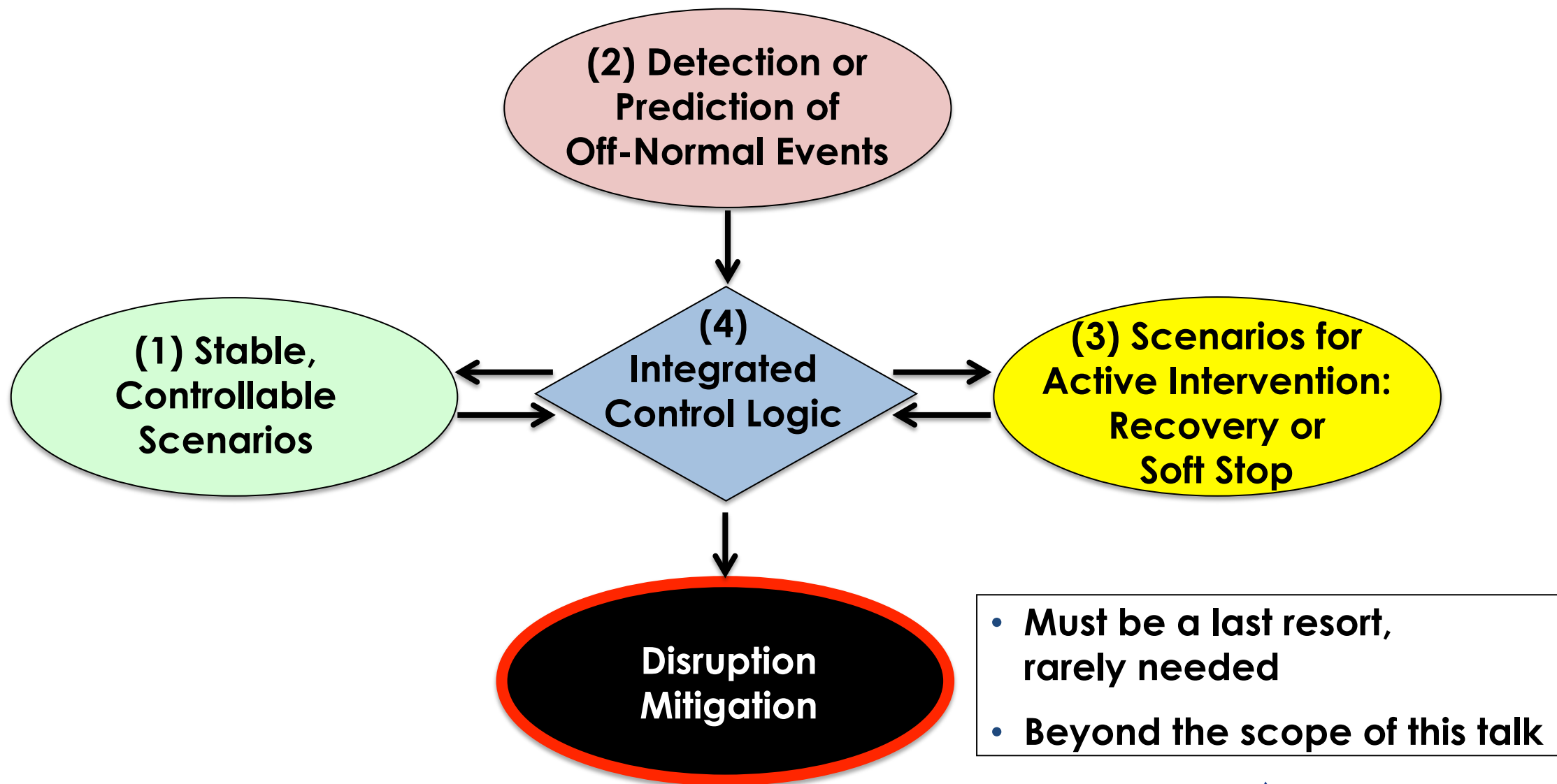
**Recent progress (2016-2018) in strategies to prevent disruptions**

*Please see the preprint for more extensive references to the important and innovative research in this area.*

# Disruption-Free Tokamak Operation is a Problem of Control

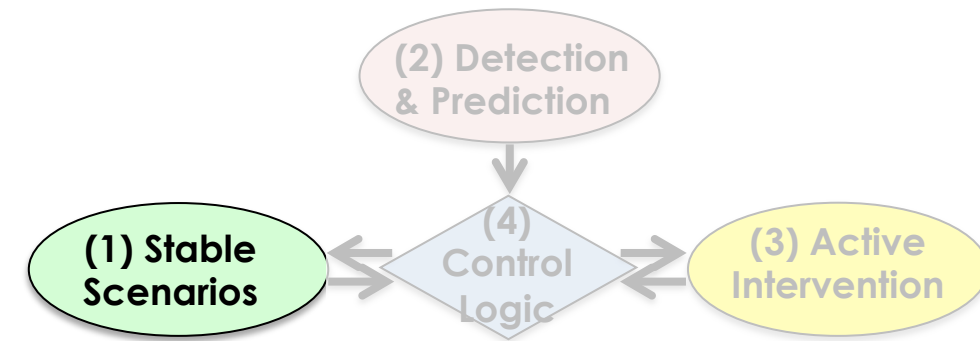


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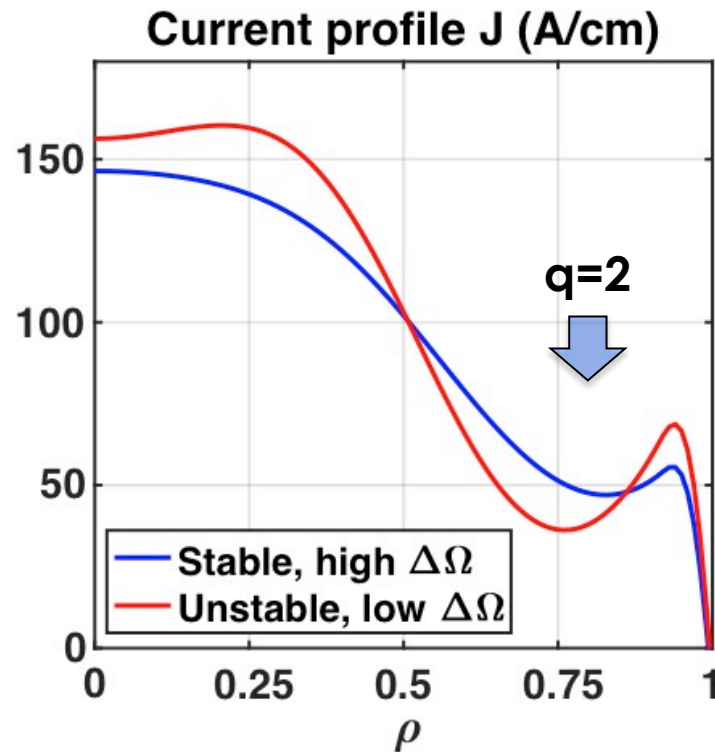
# Stable, Controllable Operation Must Be the Normal State

- **Stable plasmas in ITER-relevant scenarios**
- **Robust control to maintain the operational state**
- **Active control to expand stability limits**



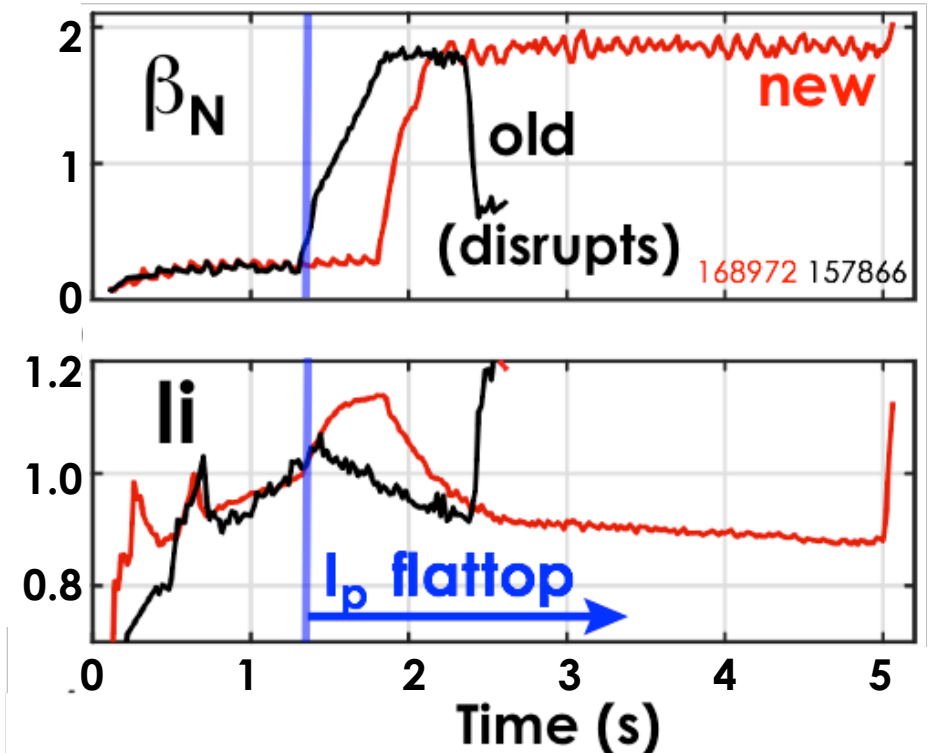
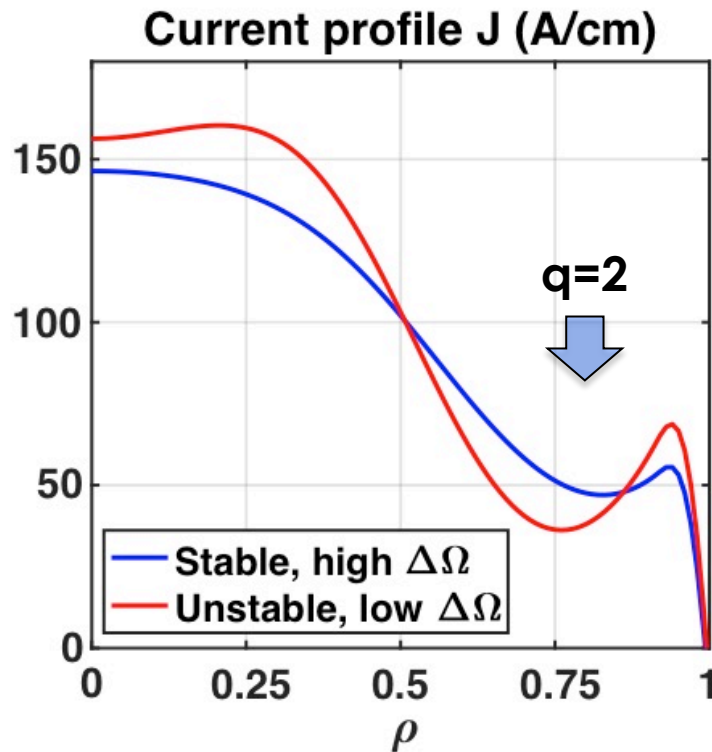
# Reproducibly Stable Plasmas Have Been Achieved in Zero-Torque ITER Baseline Scenario Discharges

- **Challenge: Maintain stability against tearing modes in ITER Baseline Scenario discharges**
  - $\beta_N \sim 1.8$ ,  $q_{95} \sim 3$       – Low NBI torque, low rotation
- **Instability correlates with deep J(r) minimum near q=2**



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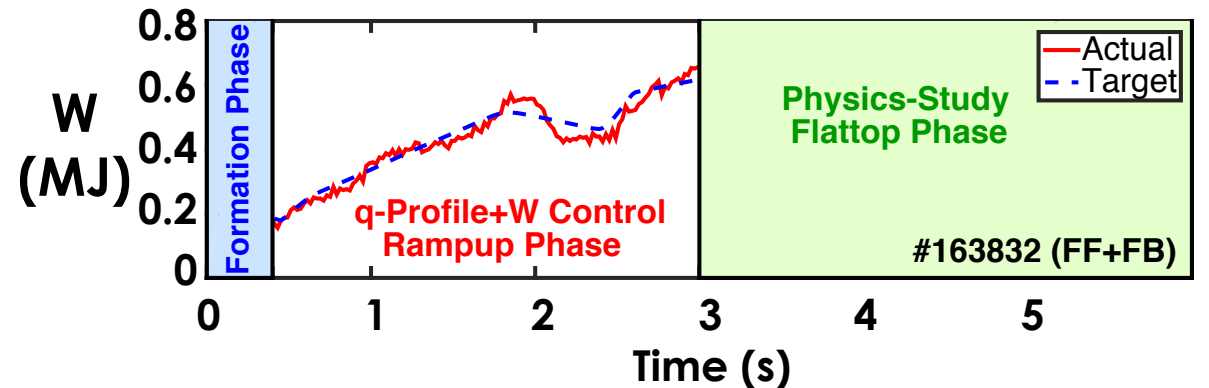
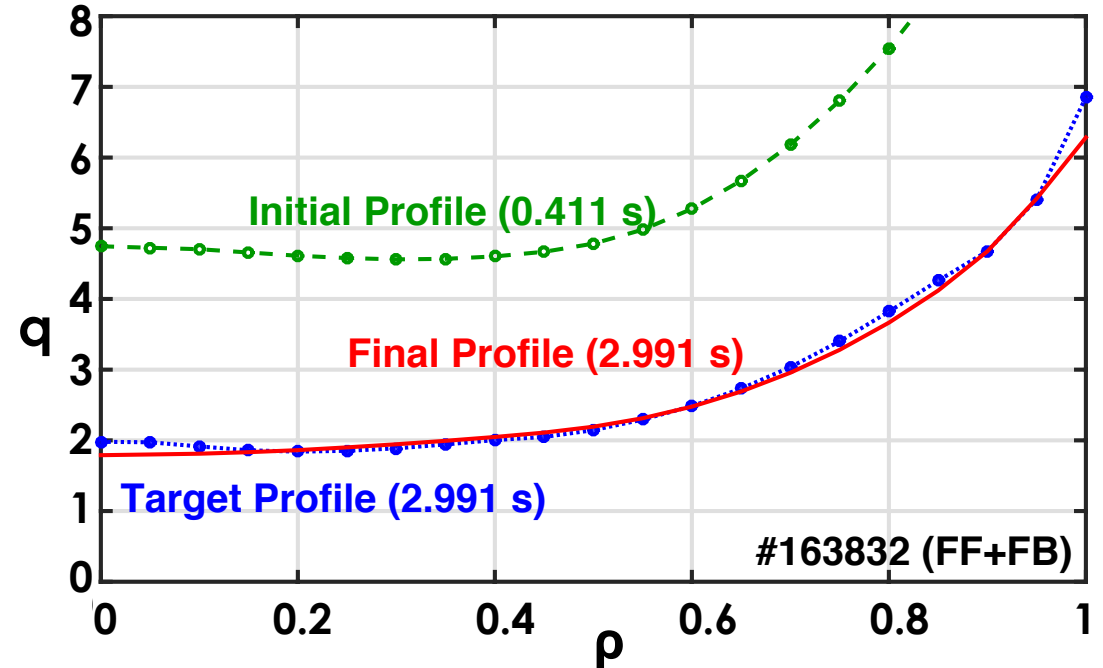
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- **Modification of early J(r) evolution improves stability**





# Profile Control is Essential to Achieve and Sustain Robustly Stable Operation

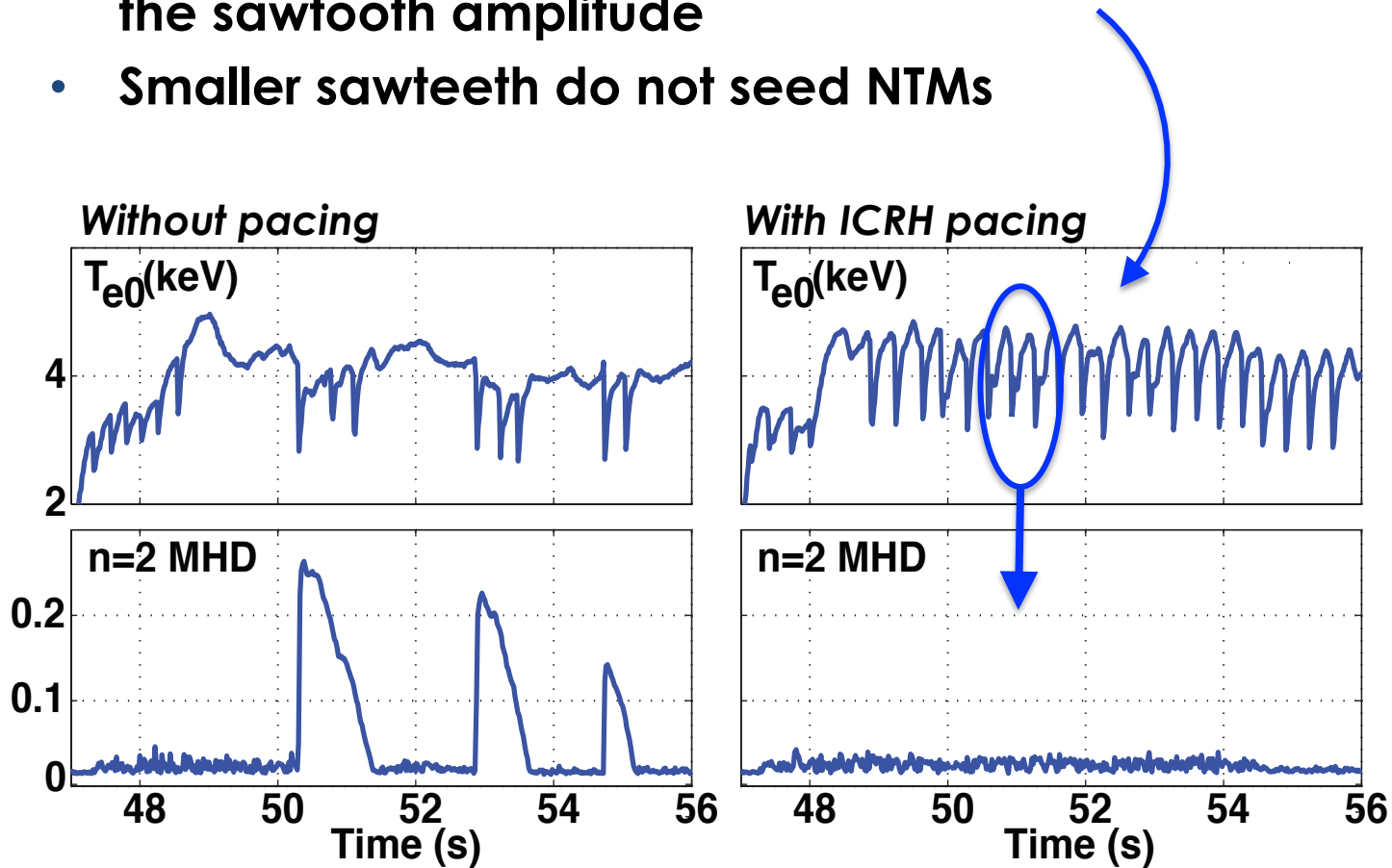
- Example: high  $q_{\min}$  steady-state scenario
- Combined feedforward and feedback scheme controls  $J(r)$  and plasma energy
- Model-based control accounts for bootstrap, EC, and NBI driven current



*Future work: Profile control in ITER baseline scenario to maintain stable  $p(r)$ ,  $J(r)$*

# Continuous Control of Instabilities Extends the Range of Stable Operation (e.g. Avoidance of Neoclassical Tearing)

- Pacing by modulated central ICRH limits the sawtooth amplitude
- Smaller sawteeth do not seed NTMs

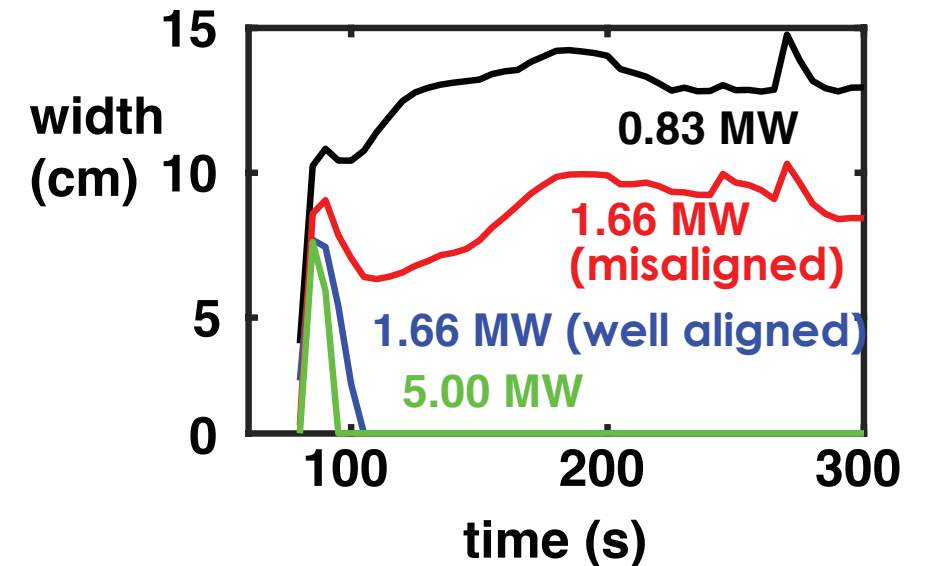
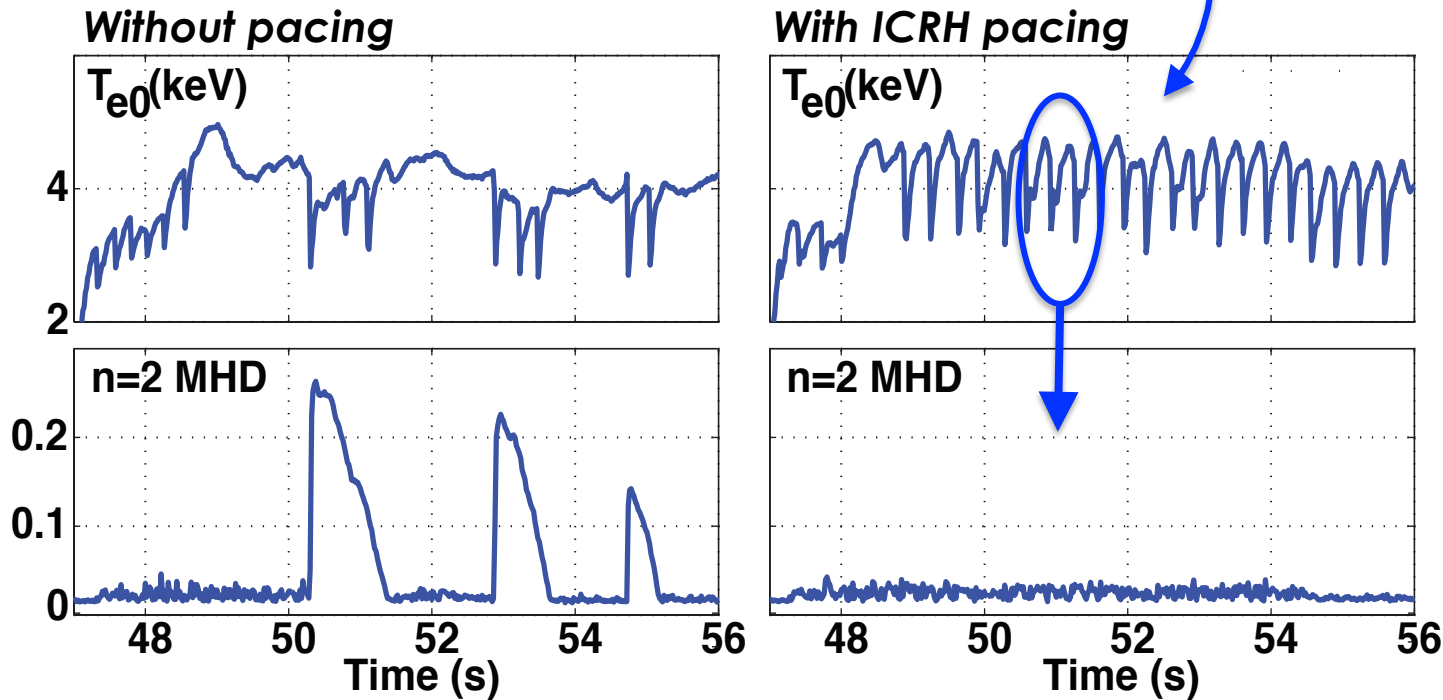


JET: E. Lerche, NF 2017

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- ITER modeling predicts that modest ECCD power can pre-emptively stabilize 2/1 NTM
  - Less power than “reactive” control
  - Requires good alignment at  $q=2$  surface



JET: E. Lerche, NF 2017

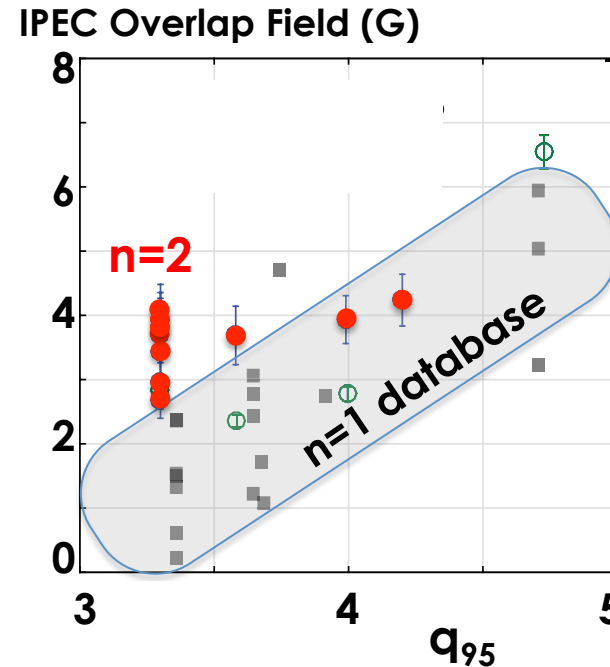
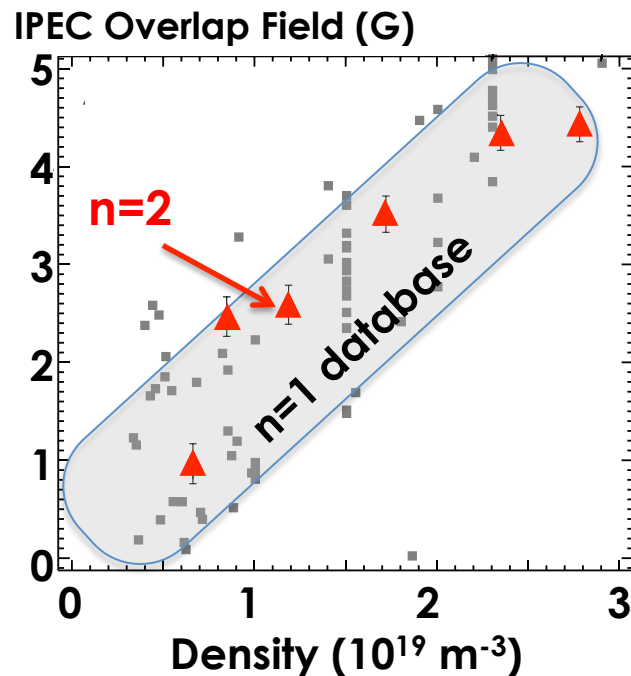
Future work: Test pre-emptive NTM stabilization with ITER-like  $q$ -profile, torque, collisionality, ...

ITER: F. Poli, NF 2018



# Prevention of Driven Tearing Modes Requires Control of 3D Configuration – i.e., Error Field Control

- **n=2 error field in low torque plasmas can penetrate directly → n=2 locked island**
  - ... or cause braking of plasma rotation → n=1 locked island
- **Thresholds for n=2 penetration in Ohmic plasmas are comparable to those for n=1**
  - vs. density (DIII-D) and vs. q95 (EAST)



*Ongoing work: Spatial spectrum for EF control with minimal braking; n=2 error field criteria for ITER.*

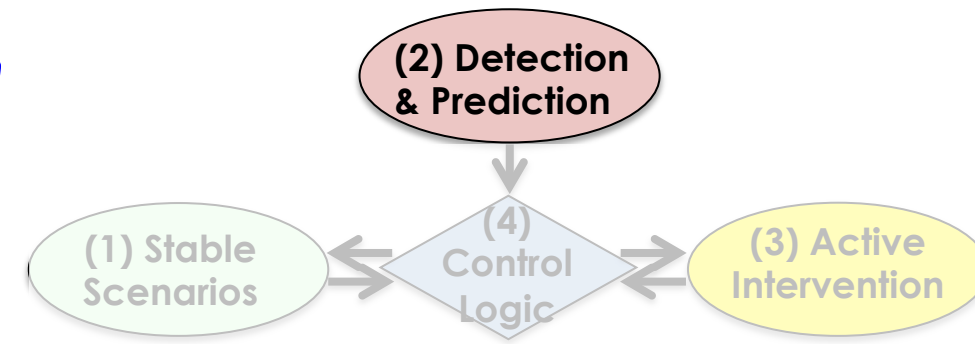
# Disruption Prevention Requires Prediction and Detection of Instabilities

## *Requirements differ from those for disruption mitigation*

- Sufficient information to decide on the response
- Sufficient time to change the discharge evolution

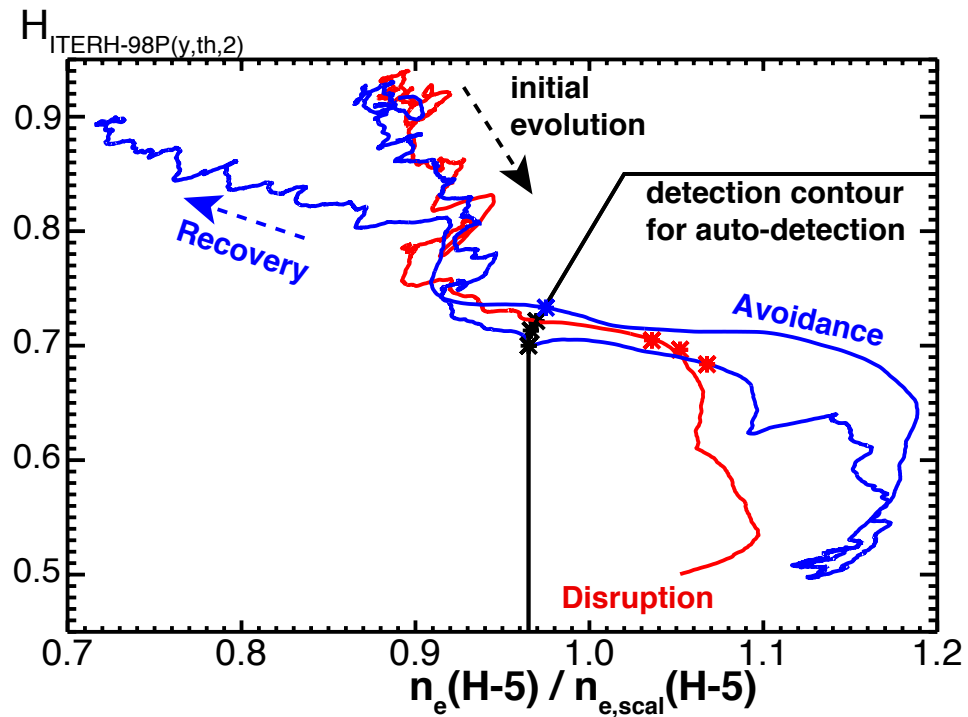
## *A broad range of approaches are being pursued*

- Physics-based predictors
- Data-driven predictors (“machine learning”)
- Direct assessment of plasma stability



# Physics-Based, Path-Oriented Algorithms Detect Early Precursors of Disruptions

- **Detection of H-mode density limit by dimensionless edge density & confinement**  
→ recovery by ECCD, reduced fueling



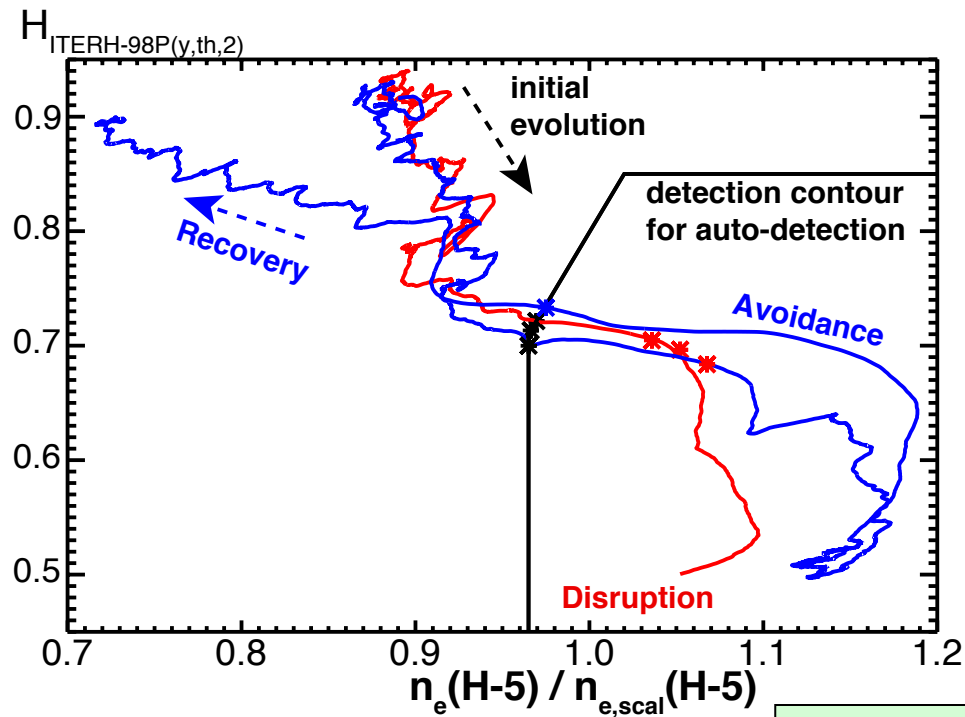
**AUG:** M. Maraschek, PPCF 2018

Also see: C. Sozzi, EX/P1-22

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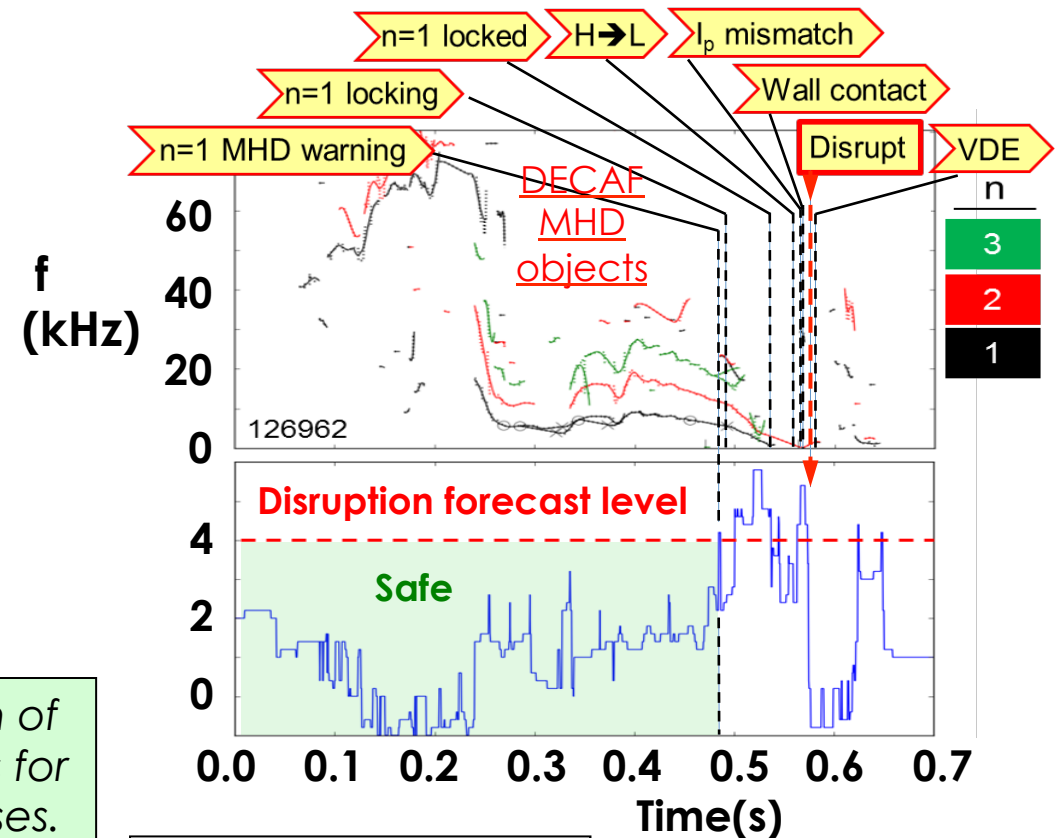
*Future work: Integration of path-oriented warnings for multiple disruption causes.*

**AUG:** M. Maraschek, PPCF 2018

Also see: C. Sozzi, EX/P1-22

- DECAF code identifies the chain of events leading to disruption

– Multiple event warnings: MHD stability, density limits, loss of control, ...

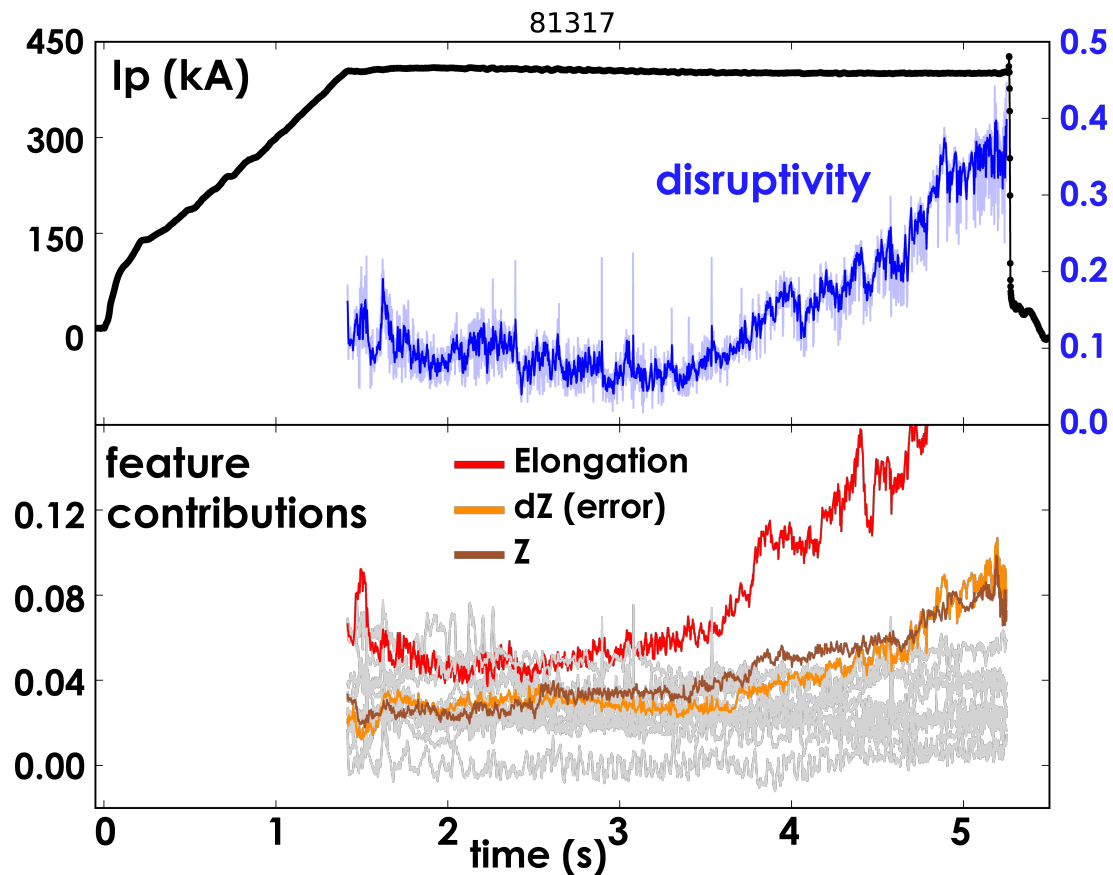


**NSTX:** S. Sabbagh, EX/P6-26



# Data-Driven (“Machine Learning”) Disruption Warnings Are Developing Toward More Quantitative Outputs

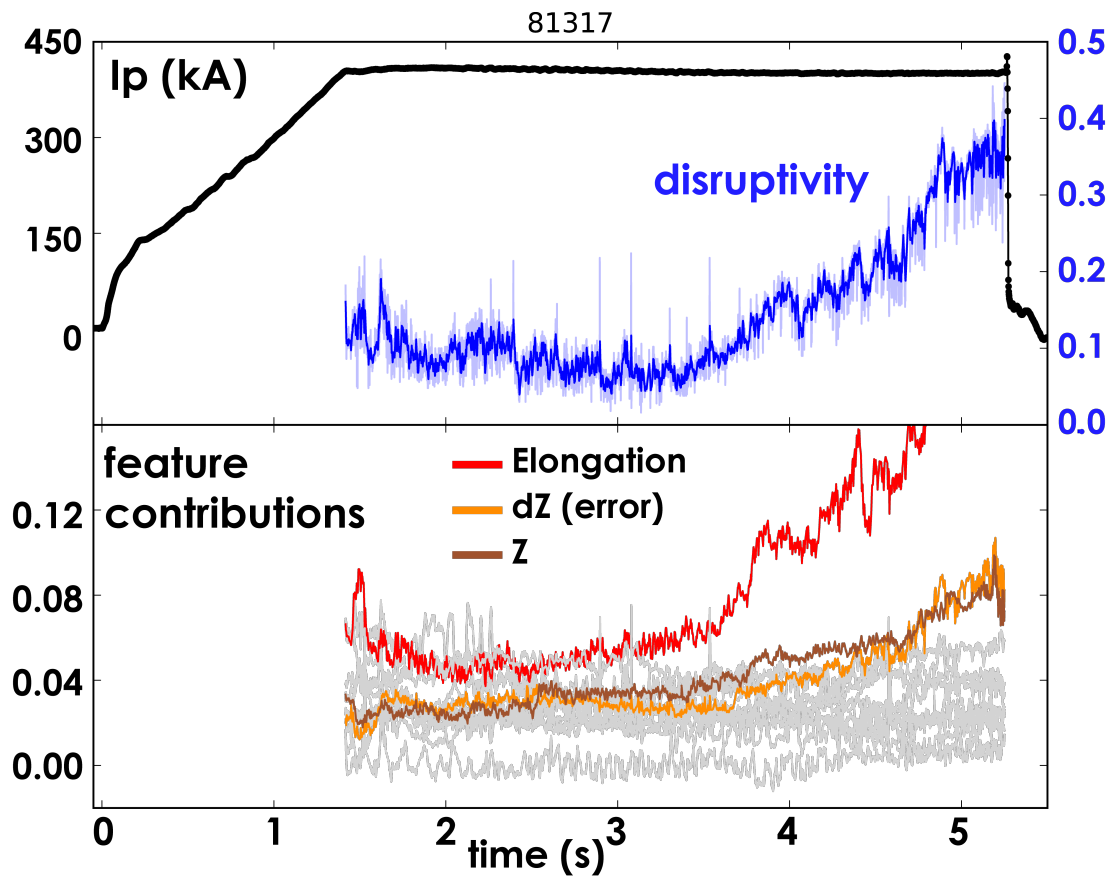
- “Random Forest” algorithm allows identification of the cause of disruption



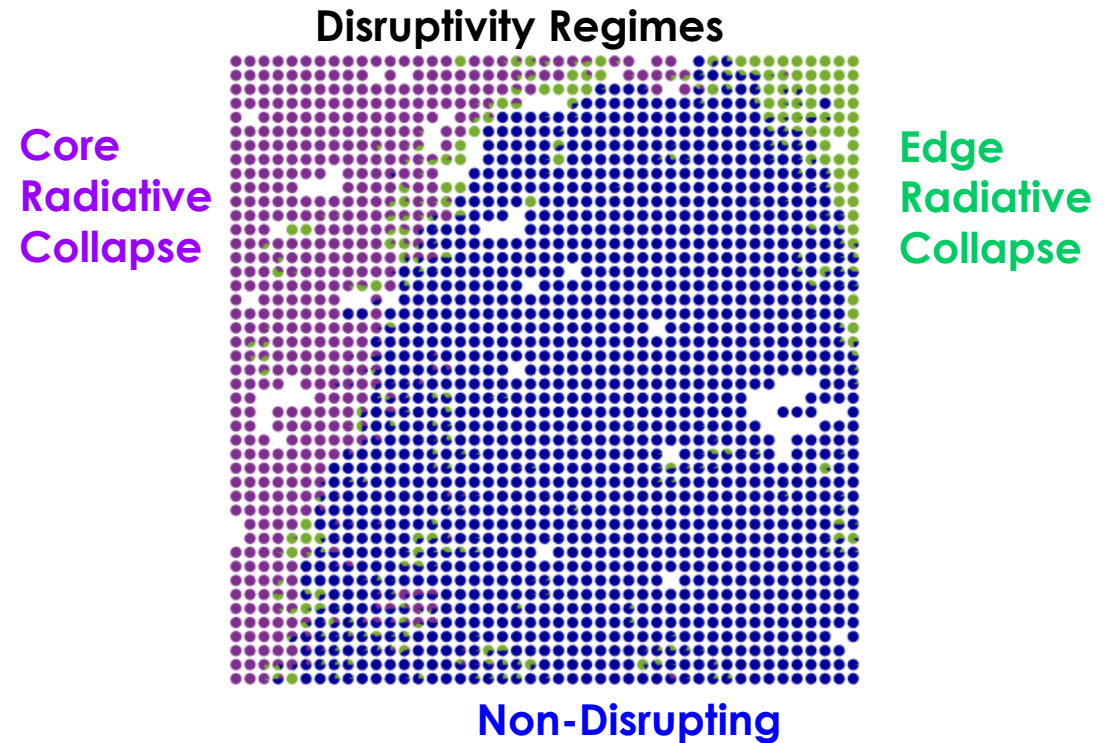


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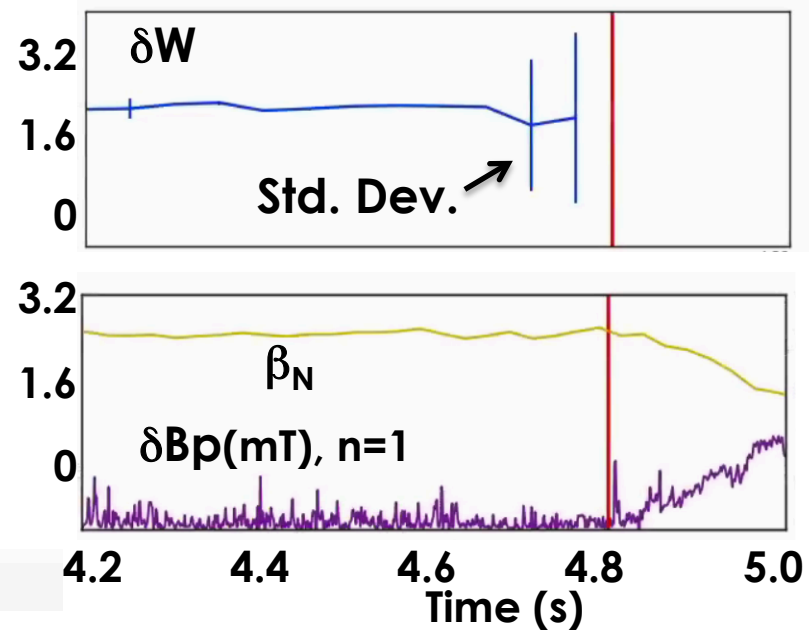
- Generative Topographic Mapping reduces multi-dimensional data to a 2D map
  - Identify and visualize limits of operation



*Ongoing work: Warnings that quantify the proximity to a limit, and identify the limit.*

# Proximity to Instability Thresholds is Directly Accessible Through Real-Time Stability Calculation or Active Probing

- **Calculation of ideal MHD stability with parallelized DCON**
  - 200 ms computation time
- **Rising uncertainty of ideal-MHD  $\delta W$  may indicate tearing mode onset**

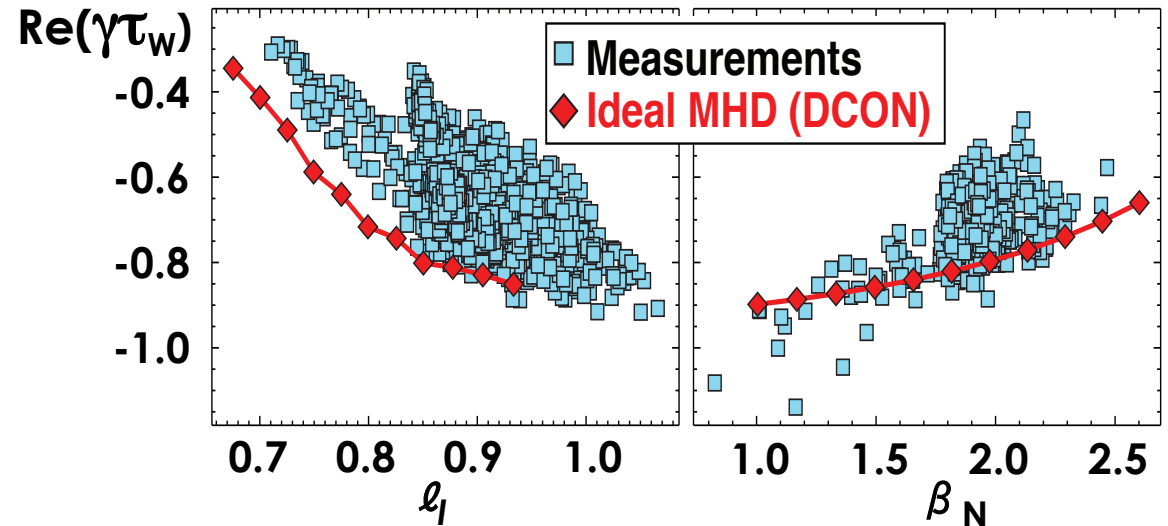
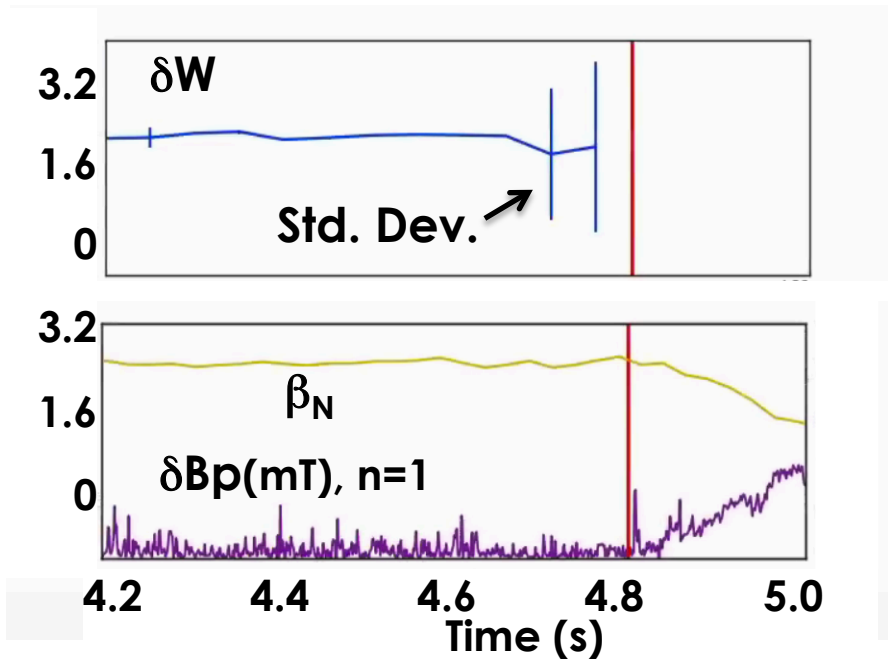


DIII-D: M. Roelofs, D. Eldon, APS 2017  
A.S. Glasser, E. Kolemen, A.H. Glasser, PoP 2018

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- **Measured damping rate of stable modes**
  - Response to 20 Hz applied  $n=1$  perturbation
- **Inferred damping rate is in qualitative agreement with ideal-MHD DCON**



*Future work: Routine use of real-time stability calculations. Relationship of calculated/measured ideal-MHD stability to onset of tearing modes?*

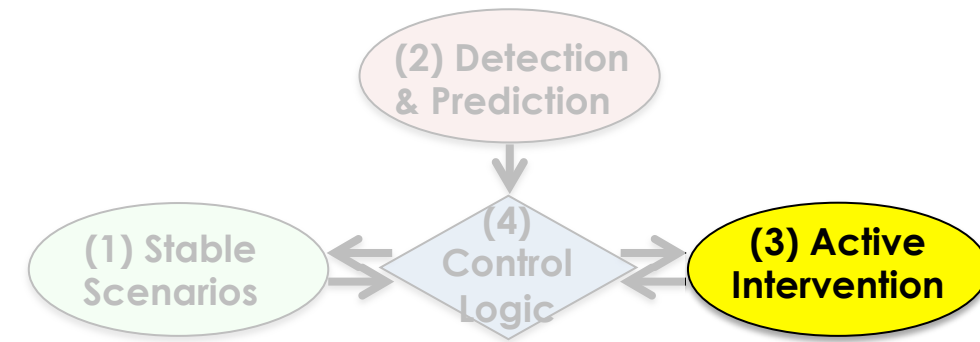
# Active Management of “Exceptions” Maintains or Recovers Stable Operation

## *Exceptions may include:*

- Off-normal plasma condition (including instability)
- Hardware faults

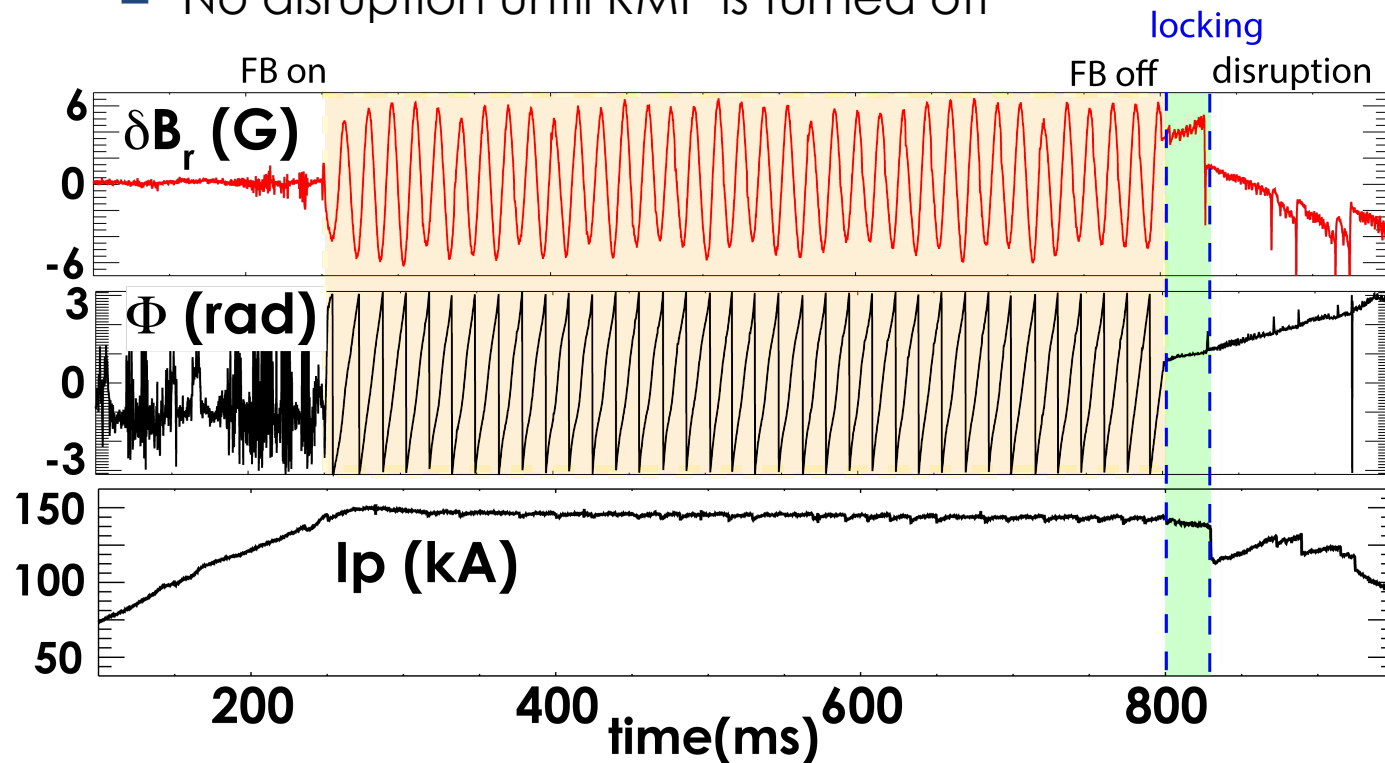
## *Possible actions include:*

- Return to normal operation
- Continue the discharge in an alternate scenario
- Controlled discharge termination
- Rapid shutdown – as a last resort



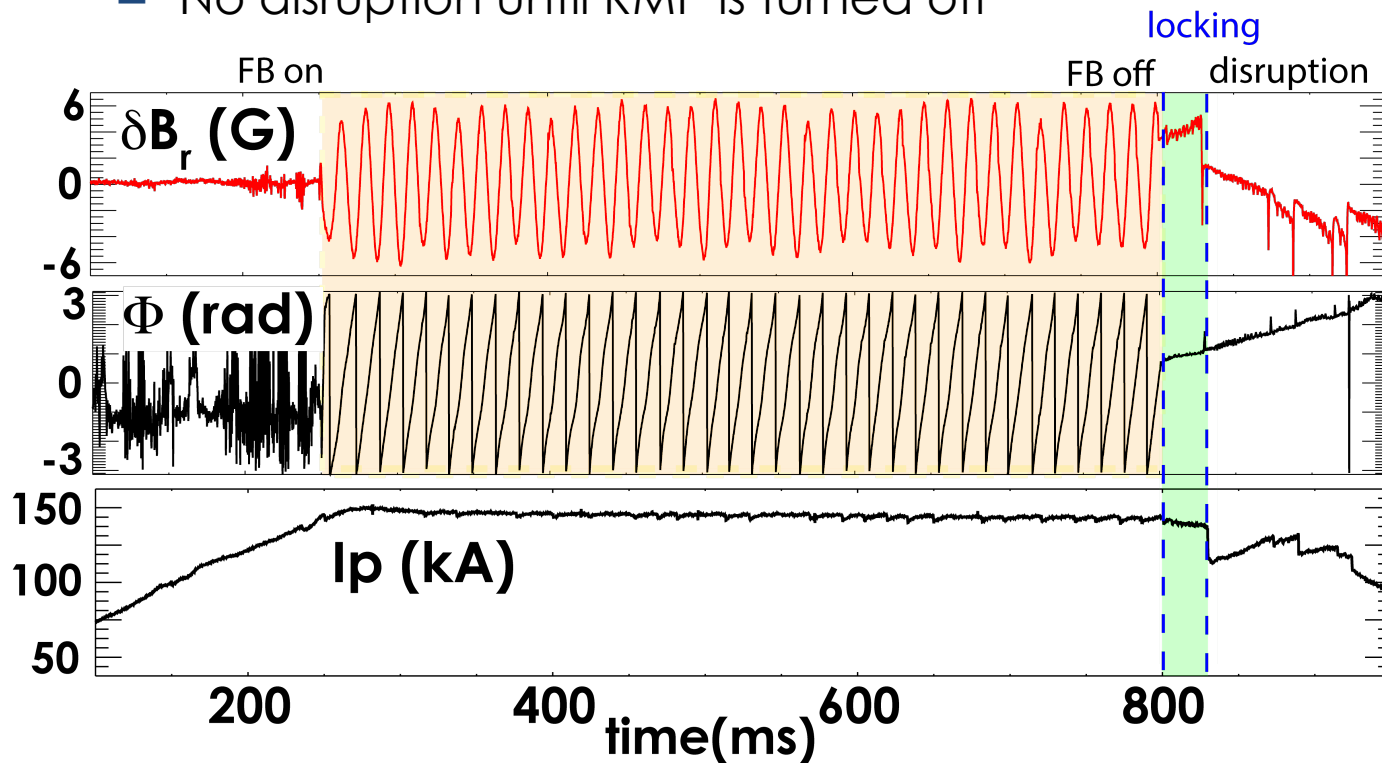
# Forced Rotation of Magnetic Islands by Applied Magnetic Perturbation Can Prevent Disruption

- **Feedback-driven RMP entrains locked mode at  $\omega\tau_{\text{wall}} \sim 1$** 
  - No disruption until RMP is turned off



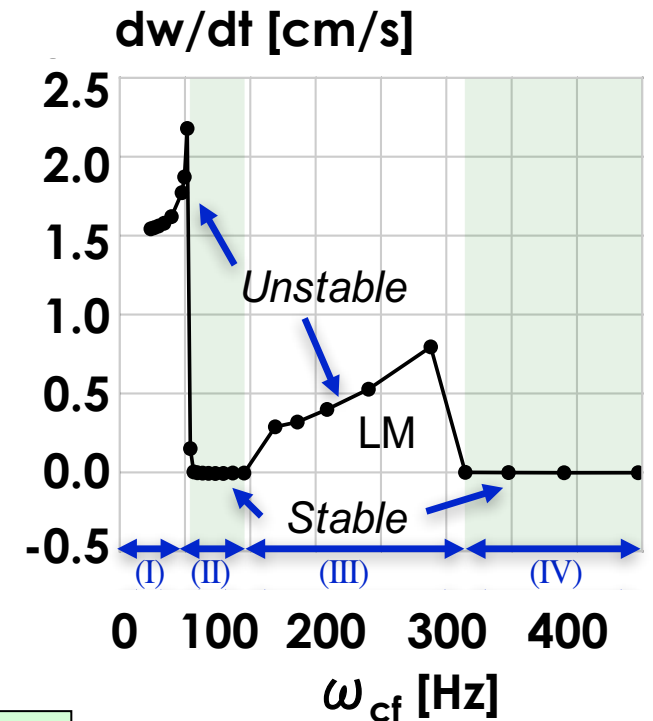
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*Future work: Validate models of stabilization by forced rotation.  
How to recover normal operation?*

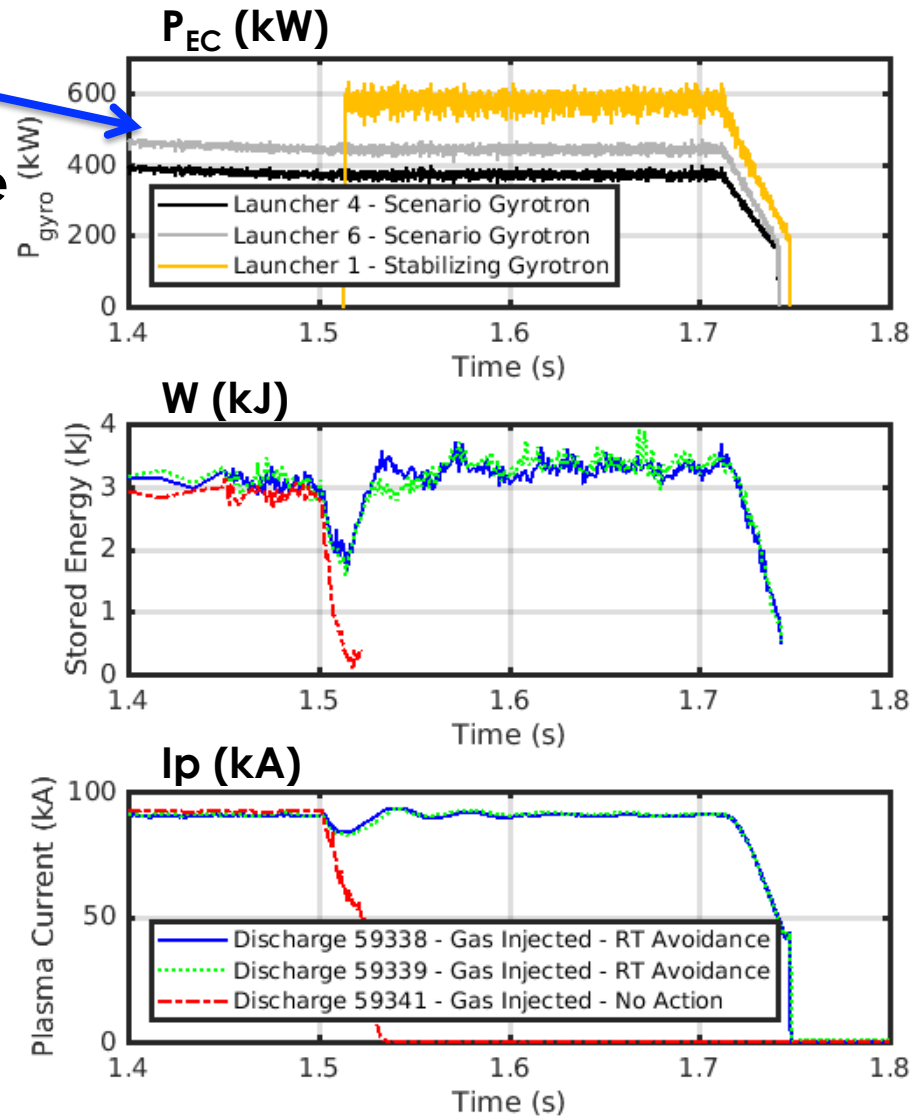
- AEOLUS reduced MHD simulation shows rotating RMP stabilizes a locked mode



JT-60SA: S. Inoue, TH/P5-24

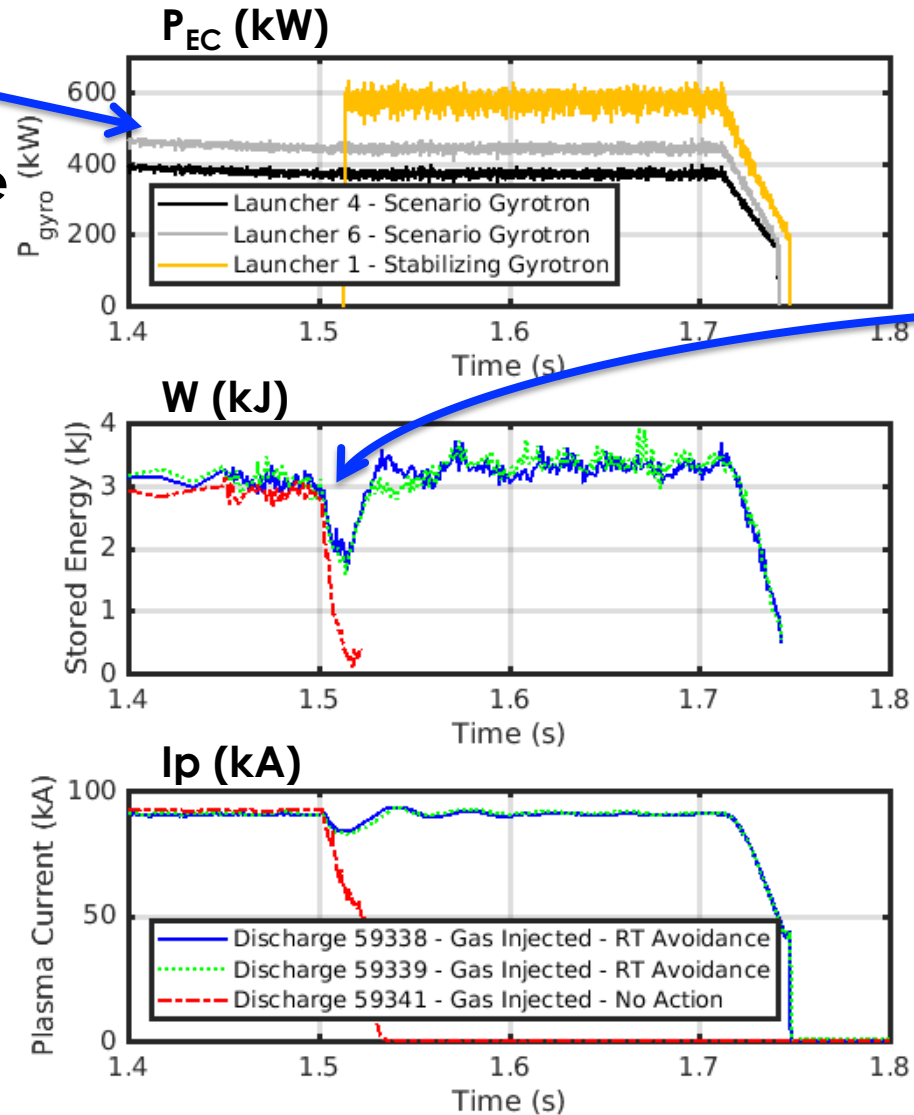
# ECCD at the Rational Surface Prevents Mode Locking After Impurity Influx

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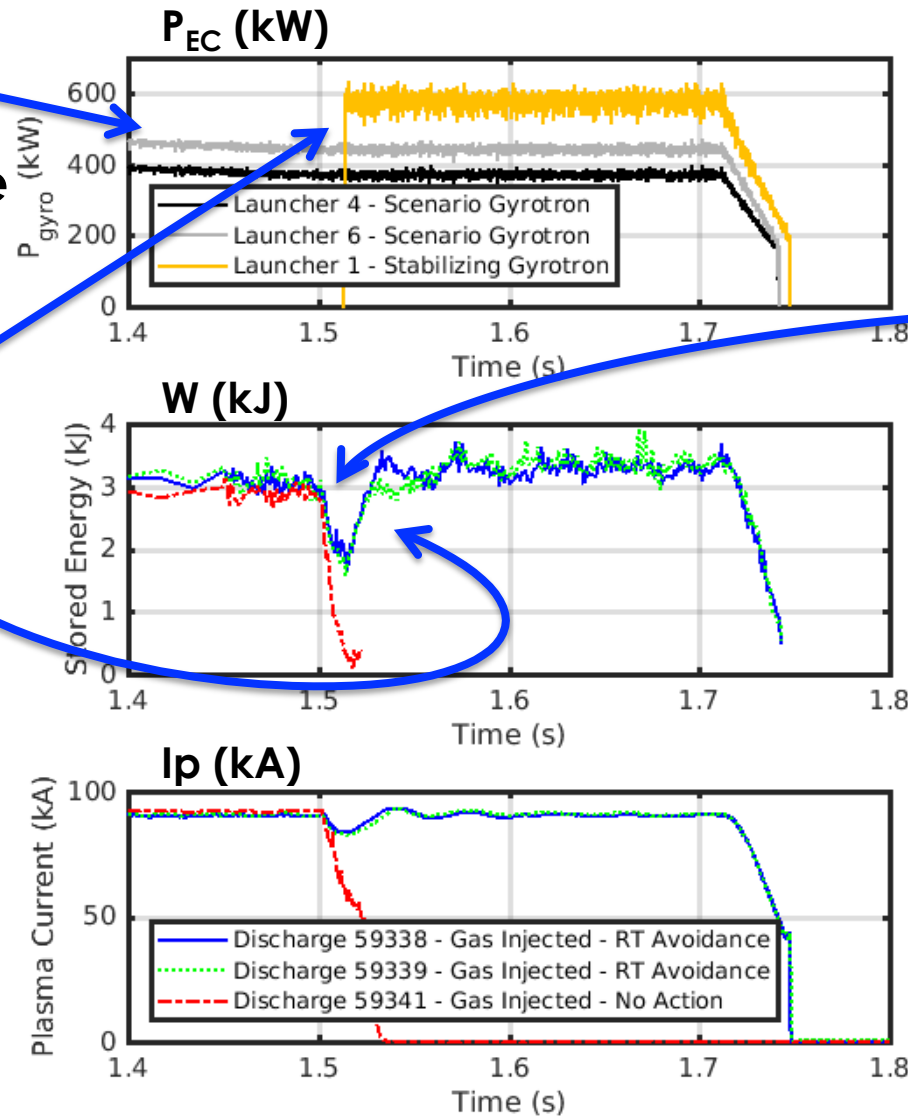


- Neon injection causes radiative energy loss
  - And increased plasma resistivity



# ECCD at the Rational Surface Prevents Mode Locking After Impurity Influx

- Core ECCD induces a pre-existing tearing mode
- Real-time triggering of ECCD at  $q=2$  enables the discharge to recover
  - Reduces 2/1 island growth



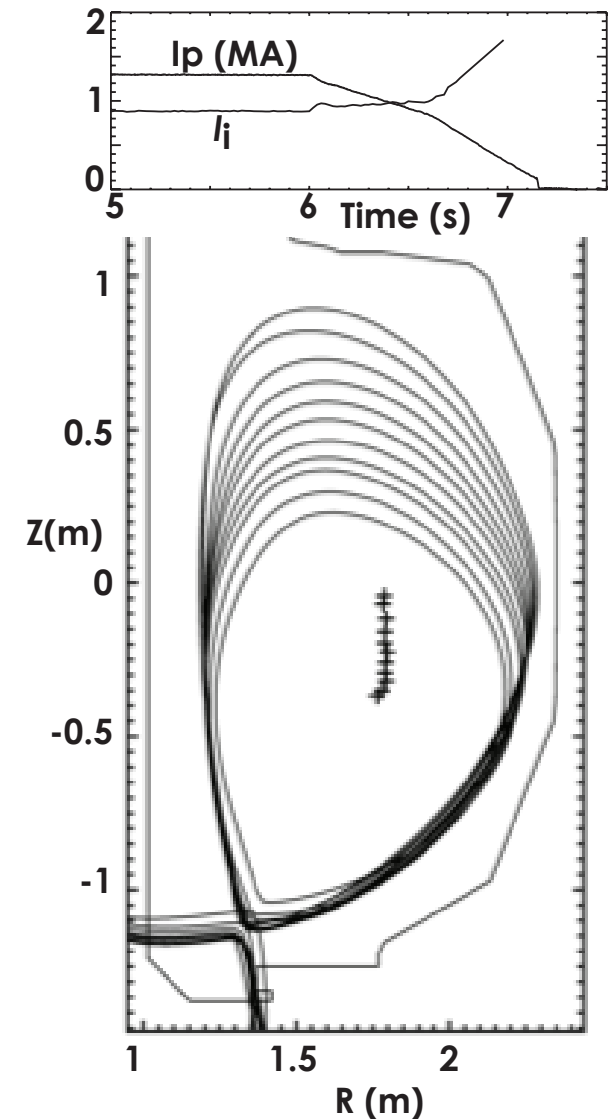
- Neon injection causes radiative energy loss
  - And increased plasma resistivity

*Future work: Role of heating vs. current drive in island stabilization. Combine EC power with forced rotation by RMP.*

# Stable Discharge Termination is a Critical Element of Disruption-Free Discharges

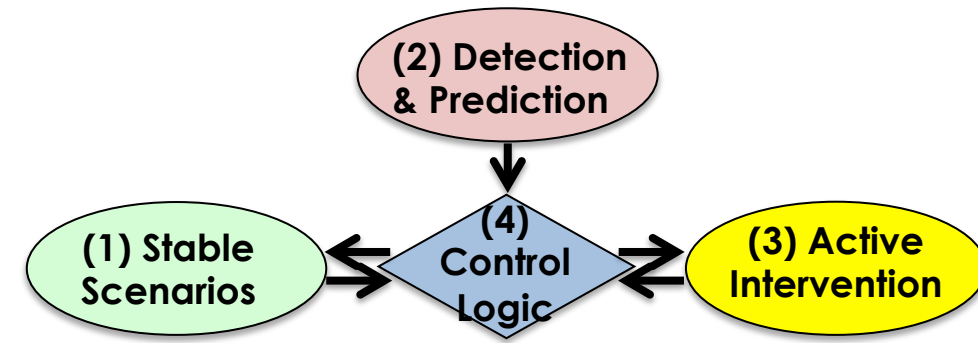
- ITER's rampdown requires reduction of elongation for vertical stability  $\rightarrow$  lower  $q$ 
  - Implications for  $n=1$  stability?
- Stable ITER-like rampdowns in DIII-D & EAST ... with  $|di_p/dt|$  up to the maximum expected for an unplanned "soft landing" in ITER
  - Core heating, ELM control, and H-L transition timing are important for stability

*Future work: Develop rampdown with a pre-existing locked mode.*



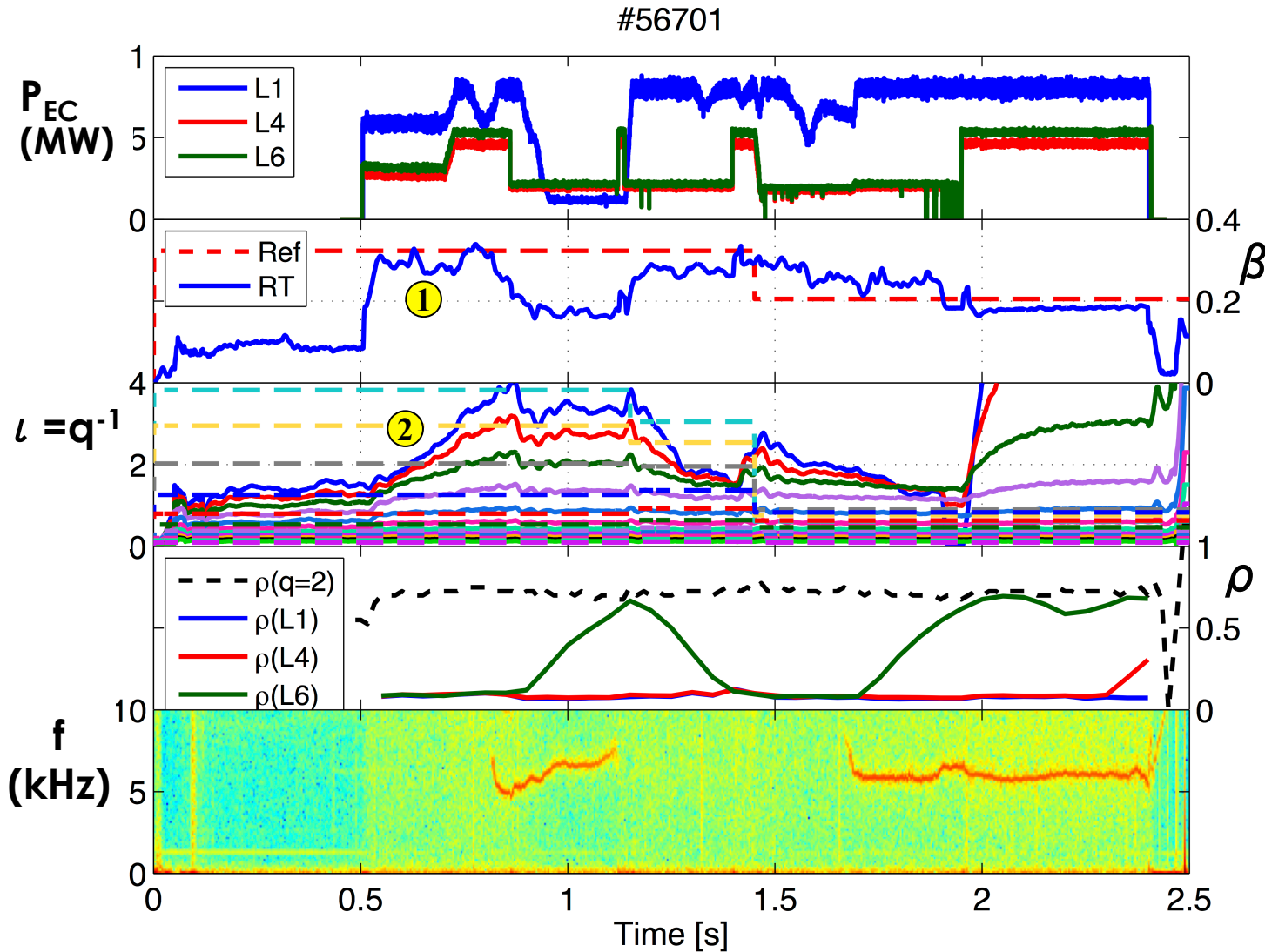
# Integrated Control Systems Supervise the Recognition of Exceptions and Necessary Responses

- Continuous control of the operational state
- Asynchronous responses to exceptions
- Change of operational state as needed



# Integrated Control Includes Actuator Sharing

## Example: ECCD for Profile Control and Tearing Mode Control

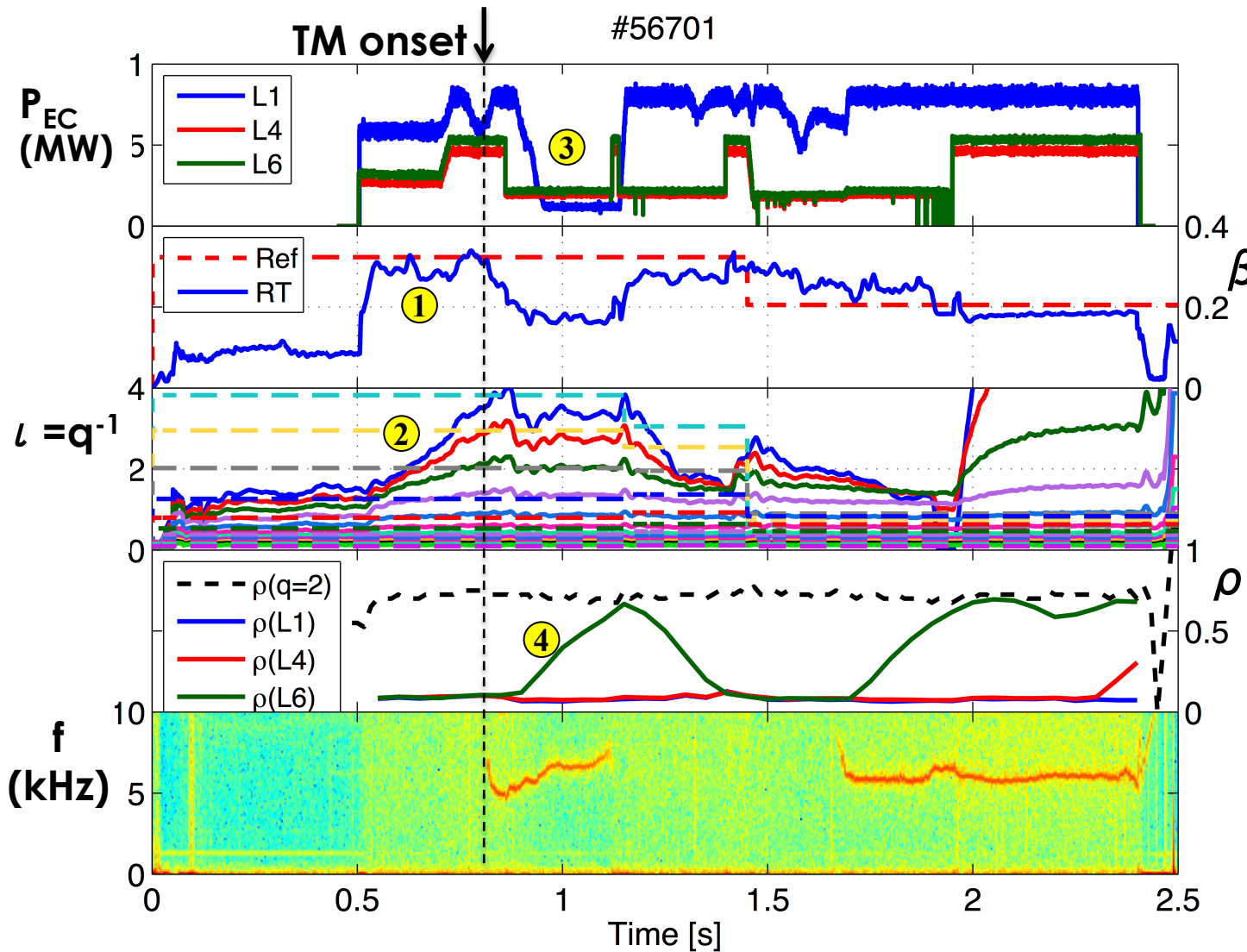


**Normal state:**

- ① EC controls  $\beta$
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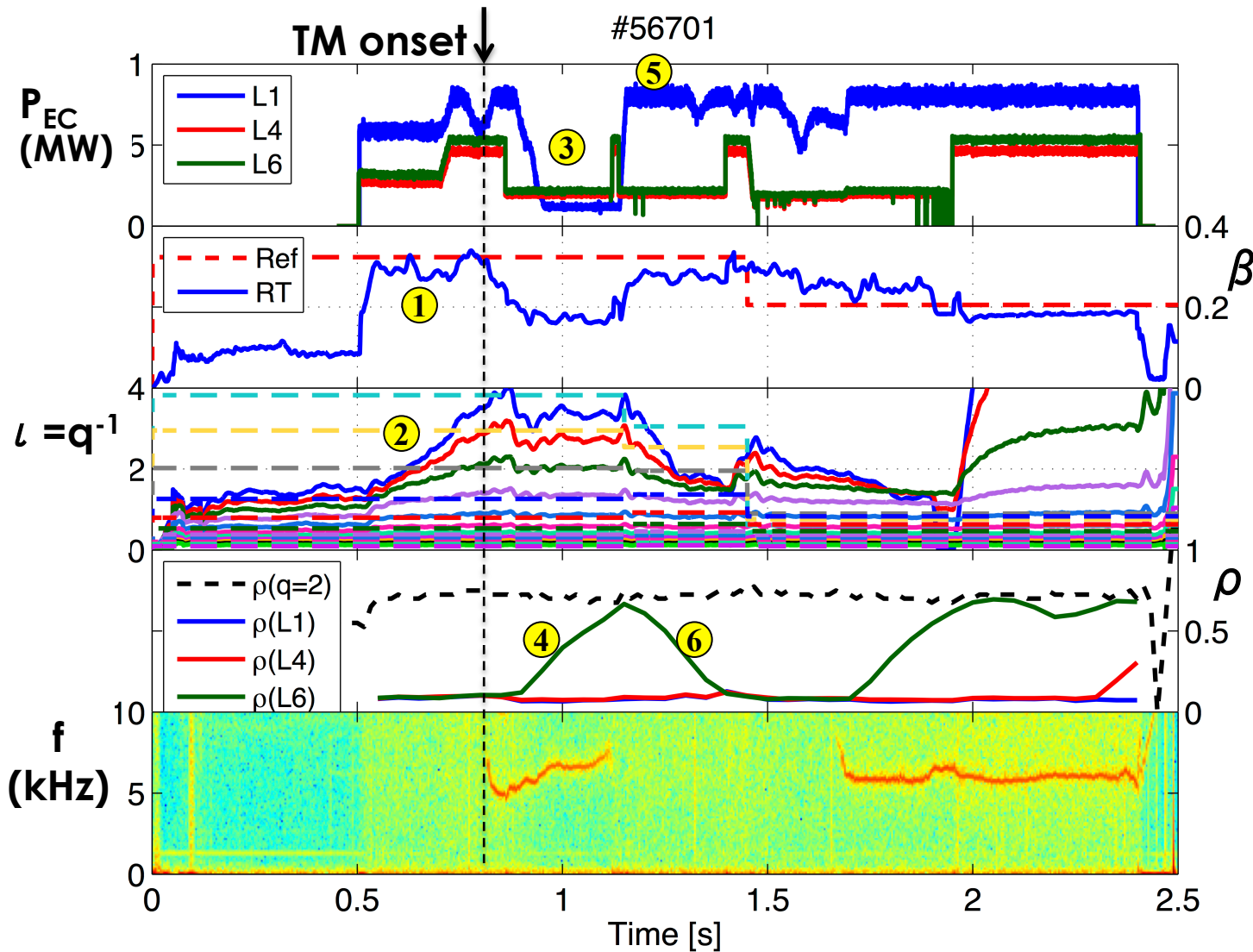
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### After Tearing Mode onset:

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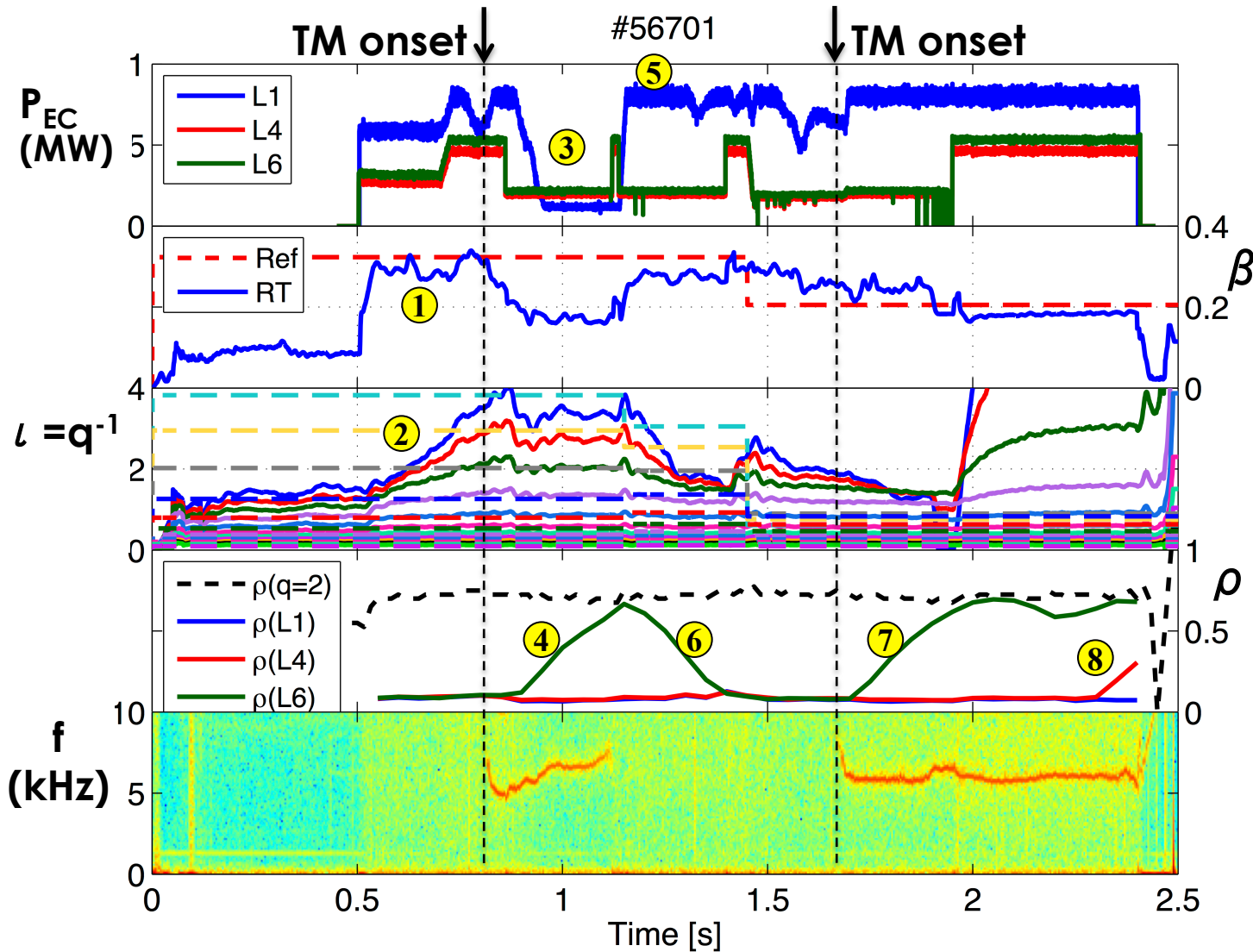
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### Tearing Mode is stabilized:

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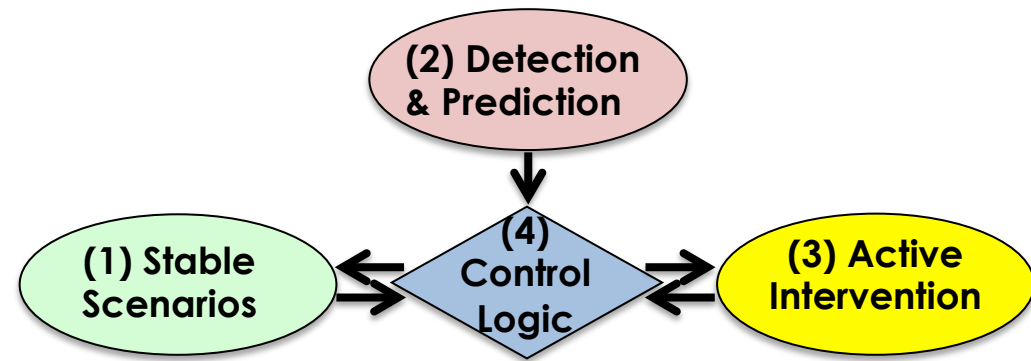
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### Tearing Mode re-appears:

- ⑦ One gyrotron re-aims to  $q=2$
- ⑧ Second gyrotron re-aims to  $q=2$

# Integrated Control Will Enable Robustly Stable Discharges with High Fusion Power in ITER

- **Key plasma physics and real-time control elements have been demonstrated**
  - Stable scenarios, real-time warning of instabilities, active management of off-normal states
- **Many challenges remain ...**
  - Physics basis of stable, high performance scenarios
  - Accurate prediction, detection, and identification of exceptions
  - Logic for asynchronous responses
  - Physics basis and control testing of intervention and recovery scenarios



- **Recommendation: Make disruption prevention routine in present tokamaks**
  - Beyond “proof of principle” → Demonstrate low rates of disruption over many shots